

# Adaptive Compressive Imaging Using Sparse Hierarchical Learned Dictionaries

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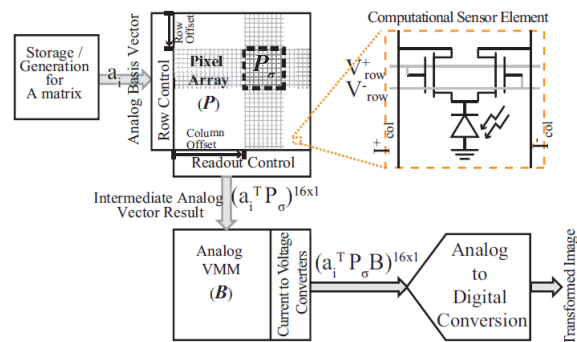
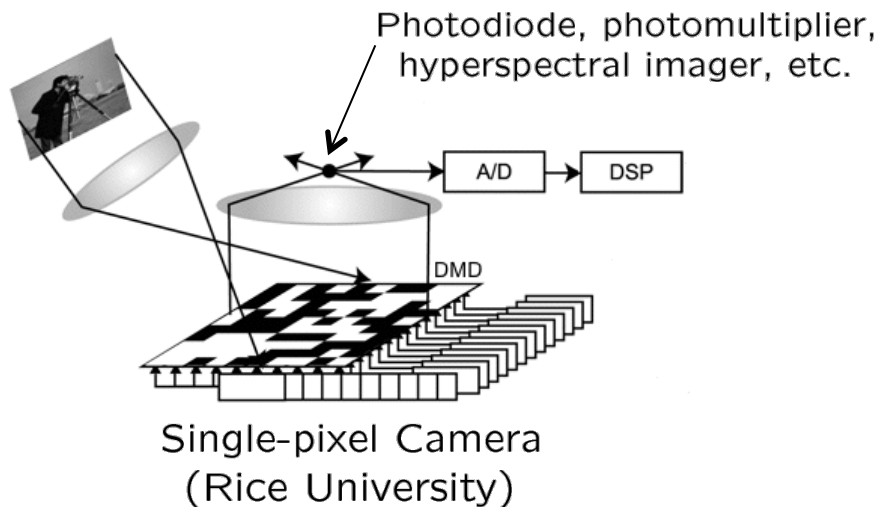
Department of Electrical and Computer Engineering



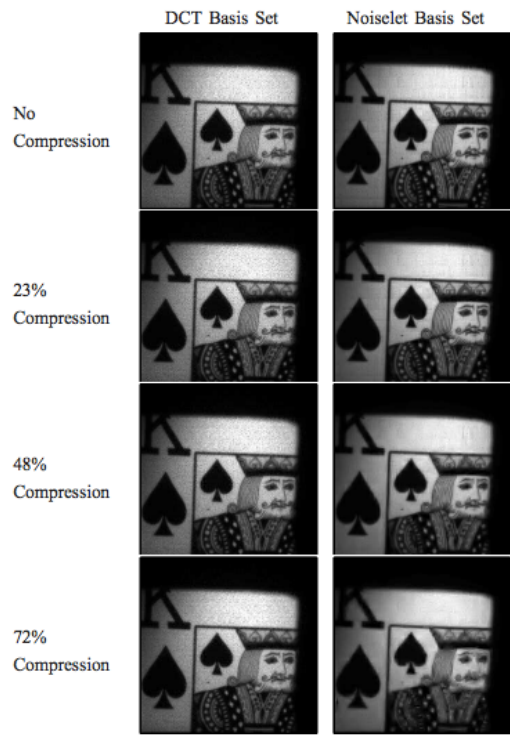
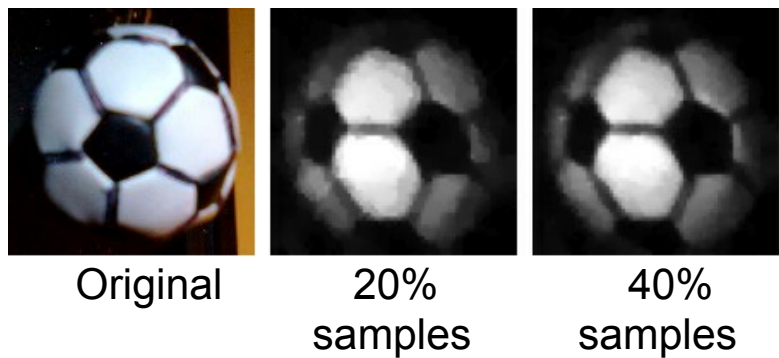
*– Motivation –*

*New Agile Sensing Platforms*

# A Host of New Agile Imaging Sensors



CMOS Separable Transform Image Sensor (Georgia Tech)



– *Overview of This Talk* –

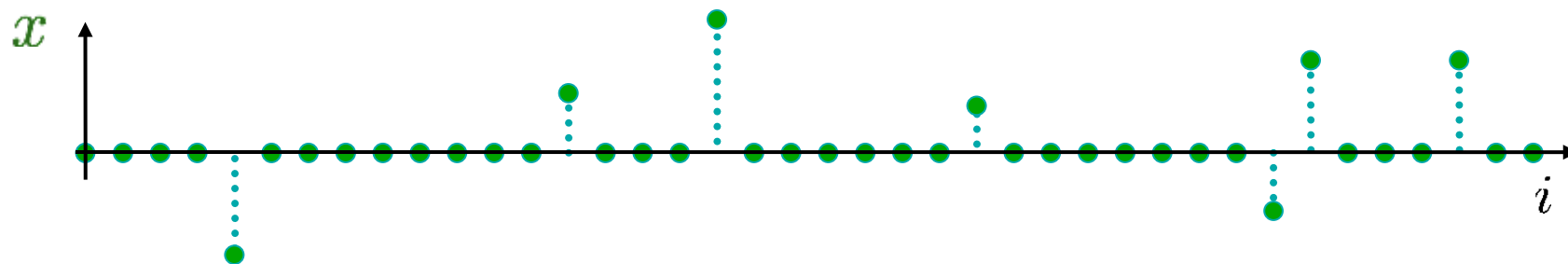
*Fusing Adaptive Sensing and Structured Sparsity  
in theory and in practice...*



– *Background* –

*Sparse Inference and Adaptive Sensing*

# A Model for Sparsity



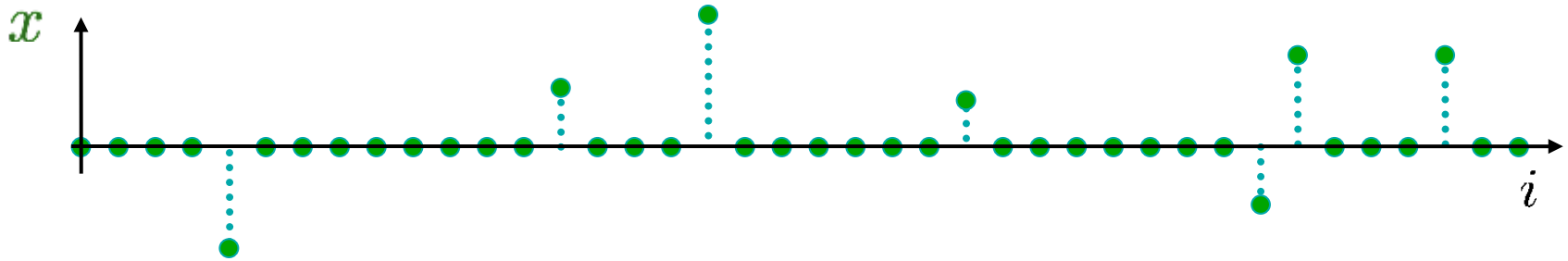
Objects of interest are vectors  $x \in \mathbb{R}^n$

Signal Support:  $\mathcal{S} \triangleq \{i : x_i \neq 0\}$

$$\text{Sparse} \Leftrightarrow |\mathcal{S}| = k \ll n$$

number of nonzero  
signal components

# A Sparse Inference Task



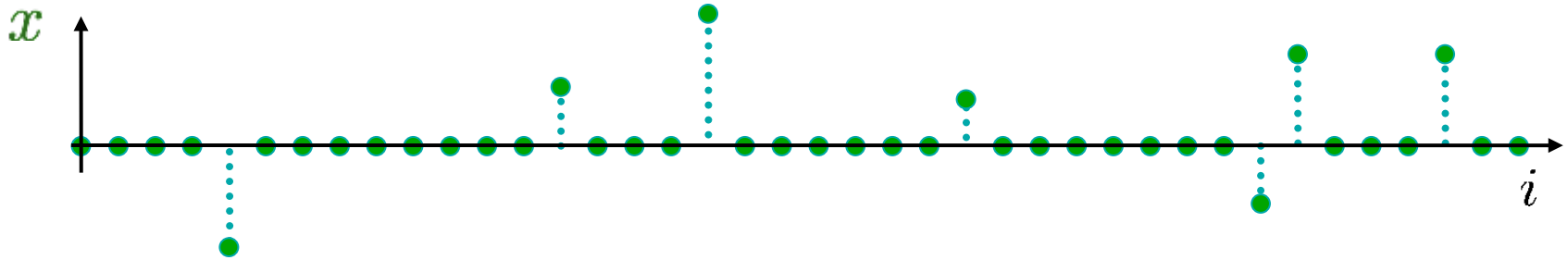
Noisy Linear Observation Model:

$$y = \Phi x + w \quad \begin{cases} \Phi \in \mathbb{R}^{m \times n} \\ w \sim \mathcal{N}(0, I_{m \times m}) \end{cases}$$

Support Recovery

Goal: Obtain an (accurate) estimate  $\hat{\mathcal{S}} = \hat{\mathcal{S}}(y, \Phi)$  of true support  $\mathcal{S}$

# A Sparse Inference Task



Noisy Linear Observation Model:

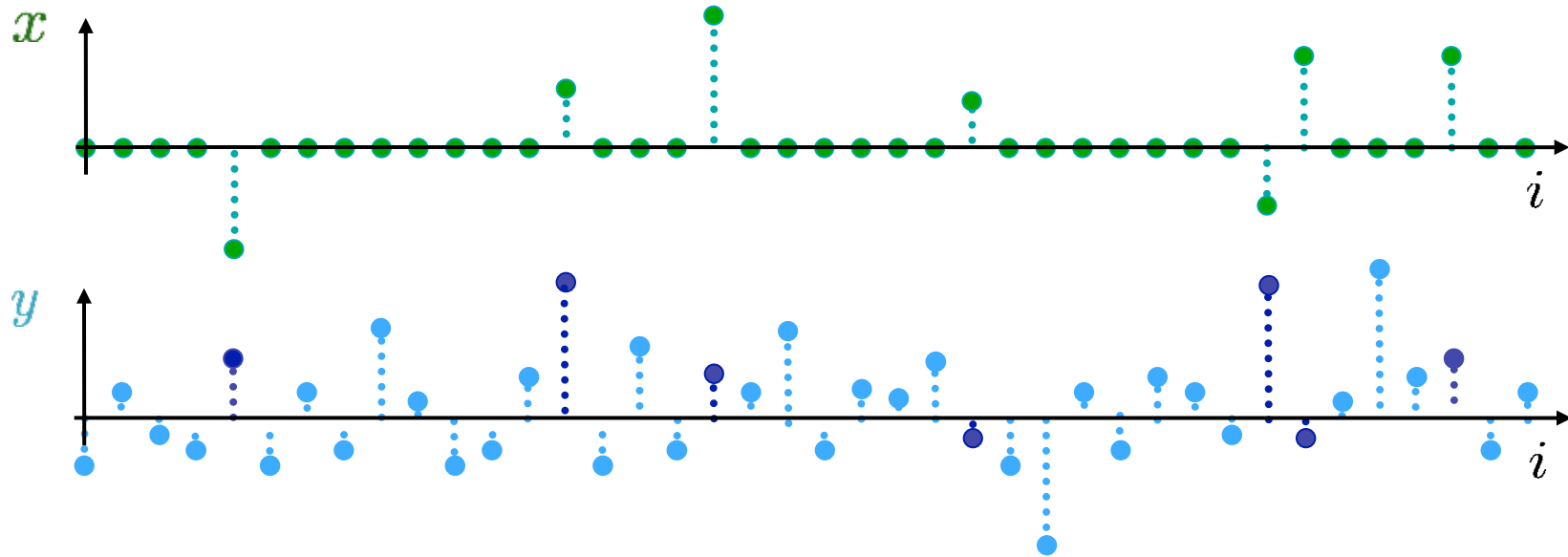
$$y = \Phi x + w \quad \begin{cases} \Phi \in \mathbb{R}^{m \times n} \\ w \sim \mathcal{N}(0, I_{m \times m}) \end{cases}$$

Assume

- “Sensing energy”  $\|\Phi\|_F^2$  fixed:  $\|\Phi\|_F^2 = R$
- $|x_i| \geq \mu$  for all  $i \in \mathcal{S}$

What conditions are necessary/sufficient for *exact* support recovery?  
(eg., such that  $P(\mathcal{S} \neq \hat{\mathcal{S}}) \rightarrow 0$  as  $n \rightarrow \infty$ )

# Exact Support Recovery?



“Point sampling”  $y = x + w$   
(Sensing energy  $R = n$ )

Necessary & Sufficient for Exact Support Recovery:

$$\mu \geq \text{const.} \sqrt{\binom{n}{R} \log n}$$

“Uncompressed” Sensing ([Donoho & Jin 2004](#); [JH, Castro, & Nowak 2010](#))

“Compressed” Sensing ([Genovese, Jin, & Wasserman 2009](#); [Aeron, Saligrama & Zhao, 2010](#))

# Conditions for Exact Support Recovery

Uncompressed /  
compressed

	Non-structured	Structured	
Non-adaptive	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right) \log n}$ (N + S)	?	Non-adaptive
Adaptive	?	?	Adaptive
	Non-structured	Structured	

“Uncompressed” Sensing (Donoho & Jin 2004; JH, Castro, & Nowak 2010)

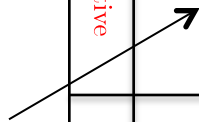
“Compressed” Sensing (Genovese, Jin, & Wasserman 2009; Aeron, Saligrama & Zhao, 2010)

Question: Can we do better by exploiting structure, or adaptivity, or both?

# Conditions for Exact Support Recovery

	Non-structured	Structured	
Non-adaptive	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right) \log n}$	?	Non-adaptive
Adaptive	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right) \log k}$ (N + S)	?	Adaptive
	Non-structured	Structured	

Uncompressed/  
Compressed



Necessity: (Castro 2012)

Sufficiency (uncompressed): (Malloy & Nowak, 2010; Malloy & Nowak, 2011)

Sufficiency (compressed): (JH, Baraniuk, Castro, & Nowak 2012, Malloy & Nowak 2013)

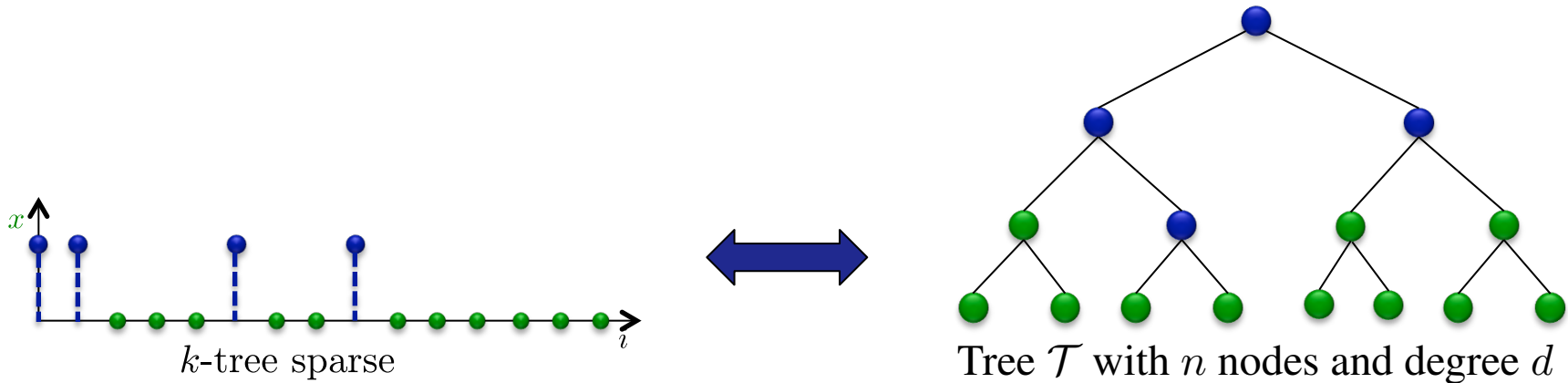
$$y = \Phi x + w \quad \begin{cases} \Phi \in \mathbb{R}^{m \times n} \\ w \sim \mathcal{N}(0, I_{m \times m}) \end{cases} \quad \|\Phi\|_F^2 = R$$

– *Beyond Simple Sparsity* –

*The Role of Structure*



# Our Focus: Tree Sparsity



Characteristics of tree structure:

- Elements of  $x$  in one-to-one correspondence with nodes of  $\mathcal{T}$
- Nonzeros of tree-sparse vector form rooted connected subtree of  $\mathcal{T}$

Question: Does tree structure help in support recovery?

# Conditions for Exact Support Recovery

	Non-structured	Structured	
Non-adaptive	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right) \log n}$	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right)}$ $(N+S)^*$	Non-adaptive
Adaptive	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right) \log k}$	?	Adaptive
	Non-structured	Structured	

Detection of simple trail  
 (uncompressed sensing)

Signal *Detection* Problem: (Arias-Castro, Candes, Helgason, & Zeitouni 2008)

# Conditions for Exact Support Recovery

The intersection of adaptivity and (tree) structure...

	Non-structured	Structured	
Non-adaptive	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right) \log n}$	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right)}$	Non-adaptive
Adaptive	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right) \log k}$	$\mu \geq \text{const.} \sqrt{\left(\frac{k}{R}\right) \log k}$ (S)	Adaptive
	Non-structured	Structured	

(A. Soni & JH, 2011)  
<http://arxiv.org/pdf/1111.6923.pdf>

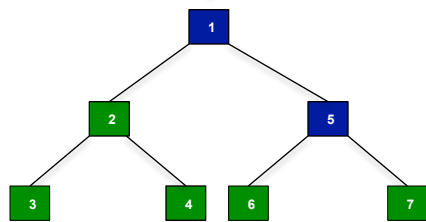
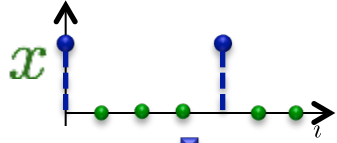


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Recent related work:

Adaptivity and Structure in finding activated blocks in a matrix (Balakrishnan, Kolar, Rinaldo, and Singh 2012)

# Adaptive Tree Sensing: An Example



$Q = \{1\}$   
 $\hat{S} = \{\emptyset\}$

$y_{(1)} = x_1 + w_{(1)}$   
suppose  $|y_{(1)}| > \tau$   
 $Q = \{2, 5\}$

$Q(1) = 2$   
 $\hat{S} = \{1\}$

$y_{(2)} = x_2 + w_{(2)}$   
suppose  $|y_{(2)}| < \tau$   
 $Q = \{5\}$

$Q(1) = 5$   
 $\hat{S} = \{1\}$

$y_{(3)} = x_5 + w_{(3)}$   
suppose  $|y_{(3)}| > \tau$   
 $Q = \{6, 7\}$

$Q(1) = 6$   
 $\hat{S} = \{1, 5\}$

$y_{(4)} = x_6 + w_{(4)}$   
suppose  $|y_{(4)}| < \tau$   
 $Q = \{7\}$

$Q(1) = 7$   
 $\hat{S} = \{1, 5\}$

$y_{(5)} = x_7 + w_{(5)}$   
suppose  $|y_{(5)}| < \tau$   
 $Q = \{\emptyset\}$

If the hypothesis test is correct at each step, then

$$m = dk + 1 = O(k)$$

Adaptive Wavelet “Tree Sensing” in the Literature:

- Non-Fourier encoded MRI (Panych & Jolesz, 1994)
- Compressive Imaging (Deutsch, Averbuch, & Dekel, 2009)

(none analyzed the case of *noisy* measurements...)

# Orthogonal Dictionaries and Tree Sparsity

Consider signals  $z \in \mathbb{R}^p$  that are sparse in a known dictionary  $D \in \mathbb{R}^{p \times n}$ . That is,  $z = Dx$ , where

- $x \in \mathbb{R}^n$  is  $k$ -sparse,
- $D$  satisfies  $D^T D = I_{n \times n}$ , and
- columns of  $D$  are  $d_j, j = 1, 2, \dots, n$

We are interested in the case where  $x$  is *tree-sparse*...

Collect (noisy) observations of  $z$  by projecting onto (scaled) columns of  $D$ . Suppose, for example, that the  $j$ -th measurement is obtained by projecting onto column  $d_i$ , then

$$y_{(j)} = \beta d_i^T z + w_{(j)}$$

where  $w_{(j)} \sim \mathcal{N}(0, 1)$ .

Nonnegative scaling factor  
(equivalently, could consider non-unit noise variance)

# Support Recovery via Adaptive Tree Sensing

**Theorem** (A. Soni & JH, 2011)

Let  $\mathcal{T}_{n,d}$  be a balanced, rooted connected tree of degree  $d$  with  $n$  nodes. Suppose that  $z \in \mathbb{R}^p$  can be expressed as  $z = Dx$ , where  $D$  is a known dictionary with orthonormal columns and  $x$  is  $k$ -sparse. Further, suppose the support of  $x$  corresponds to a rooted connected subtree of  $\mathcal{T}_{n,d}$ . Observations of  $z$  are of the form of projections of  $z$  onto columns of  $D$ .

Let the index corresponding to the root of  $\mathcal{T}_{n,d}$  be known, and apply the top-down tree sensing procedure with threshold  $\tau$  and scaling parameter  $\beta$ . For any  $c_1 > 0$  and  $c_2 \in (0, 1)$ , there exists a constant  $c_3 > 0$  such that if

$$\mu = \min_{i \in \mathcal{S}} |x_i| \geq \sqrt{c_3 \beta^{-2} \log k}$$

and  $\tau = c_2 \mu \beta$ , the tree sensing procedure collects  $m = dk + 1$  measurements, and produces a support estimate  $\hat{\mathcal{S}}$  that equals  $\mathcal{S}$  with probability at least  $1 - k^{-c_1}$ .

Choose  $\beta = \sqrt{\frac{R}{(d+1)k}}$ , then the theorem guarantees exact support recovery (whp) when

$$\mu \geq \sqrt{c_3 (d+1) \left(\frac{k}{R}\right) \log k}$$

# Conditions for Exact Support Recovery

The intersection of adaptivity and (tree) structure...

	Non-structured	Structured	
Non-adaptive	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right) \log n}$	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right)}$ (*conjecture for support recovery)	Non-adaptive
Adaptive	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right) \log k}$	$\mu \geq \text{const.} \sqrt{\left(\frac{k}{R}\right) \log k}$ (S)	Adaptive
	Non-structured	Structured	

(A. Soni & JH, 2011)  
<http://arxiv.org/pdf/1111.6923.pdf>



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– *LASeR* –

*Learning Adaptive Sensing Representations*



# Beyond Wavelet Trees: *Learned* Representations

Given training data  $Z \in \mathbb{R}^{p \times q}$ , want to *learn* a dictionary  $D$  so that

$$Z \approx DX, \quad D \in \mathbb{R}^{p \times n}, \quad X \in \mathbb{R}^{n \times q},$$

and each column of  $X$ ,  $x_i \in \mathbb{R}^n$ , is tree-sparse in  $\mathcal{T}_{n,d}$ .

Pose this as an optimization:

$$\{D, X\} = \arg \min_{D \in \mathbb{R}^{p \times n}, D^T D = I_{n \times n}, \{x_i\}} \sum_{i=1}^q \|z_i - Dx_i\|_2^2 + \lambda \Omega(x_i)$$

The regularization term is  $\Omega(x_i) = \sum_{g \in \mathcal{G}} \omega_g \|(x_i)_g\|$ , where

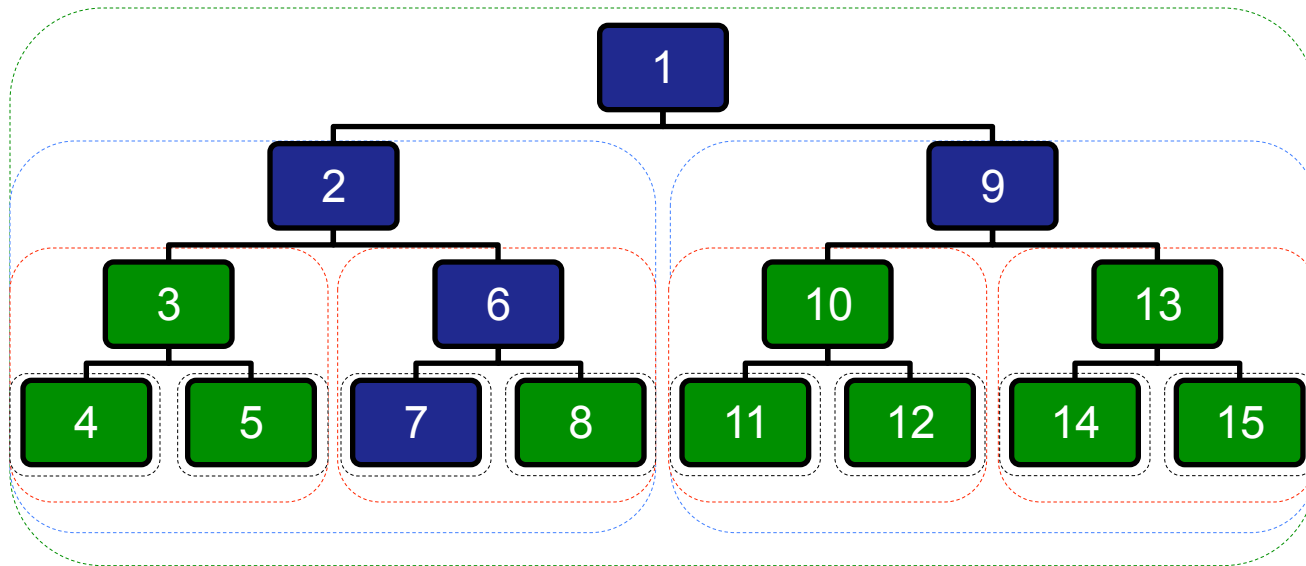
- $\mathcal{G}$  denotes a set of (overlapping) groups of indices for  $x$ ,
- $(x_i)_g$  is  $x_i$  restricted to the indices in the group  $g \in \mathcal{G}$ ,
- $\omega_g$  are non-negative weights, and
- the norm can be, eg.,  $\ell_2$  or  $\ell_\infty$

**Learning an Orthonormal Basis  
with Structure**

Solve by *alternating minimization* over  $D$  and  $X$  (Jenatton, Mairal, Obozinski, & Bach, 2010)  
Sparse Modeling Software (SPAMS): <http://spams-devel.gforge.inria.fr/>

# Group Specifications to Enforce Tree Structure

Example: Binary Tree, 15 nodes, 4 levels...

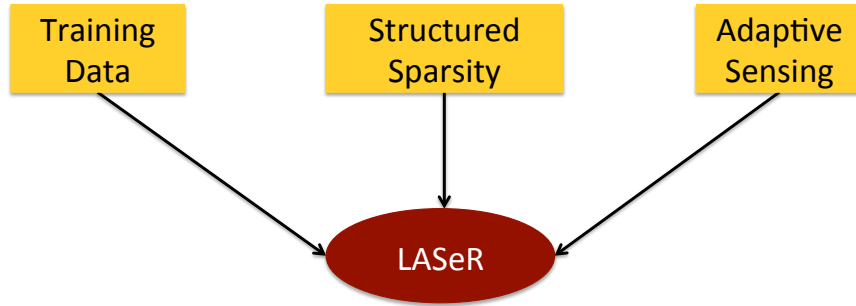


Number of groups same as number of nodes (but varying sizes)

– *LASeR* –

*An Illustrative Example*

# Learning Adaptive Sensing Representations



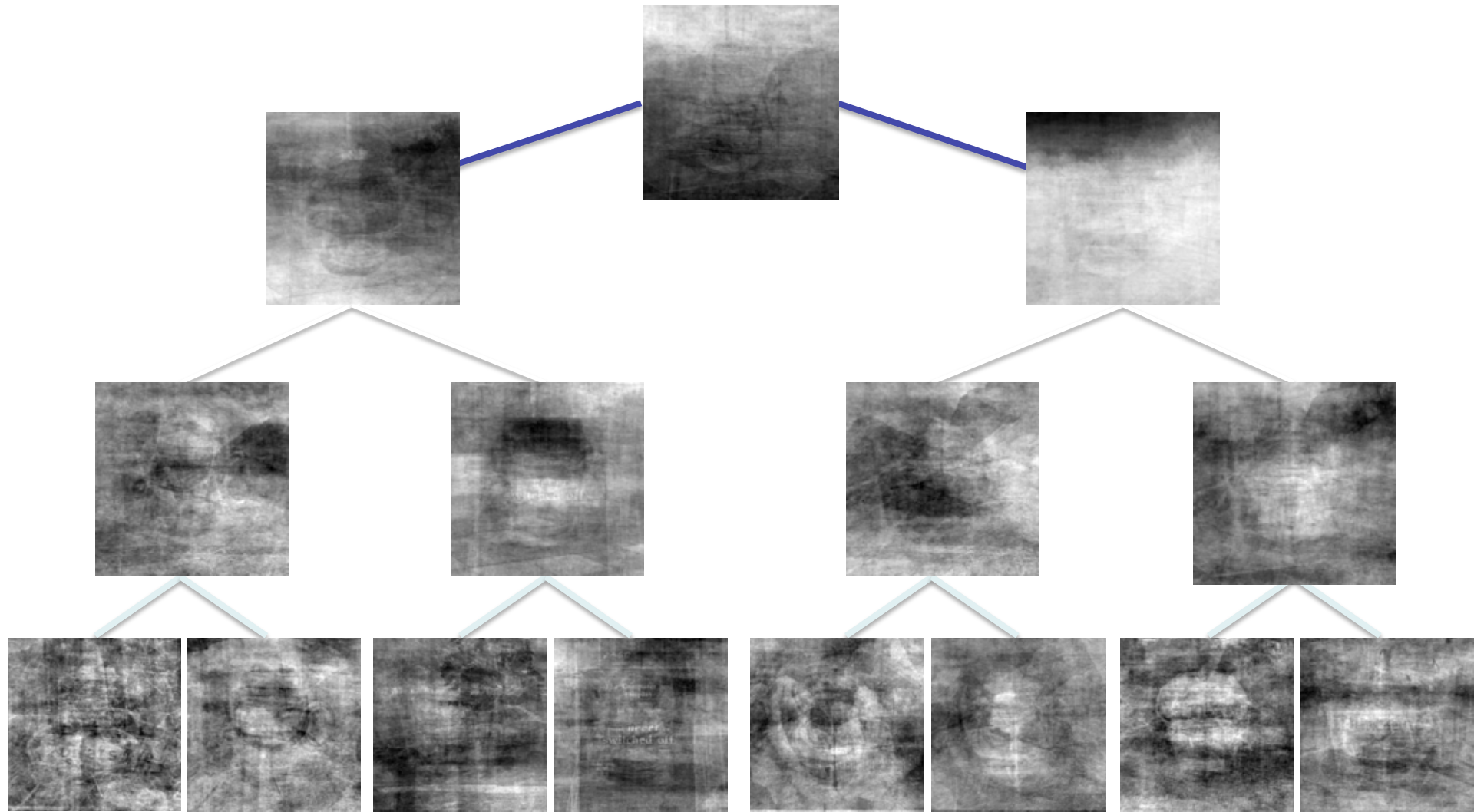
Learn representation for 163 images from Psychological Image Collection at Stirling (PICS) <http://pics.psych.stir.ac.uk/>

LASeR: Learning Adaptive Sensing Representations

Example images ( $128 \times 128$ )



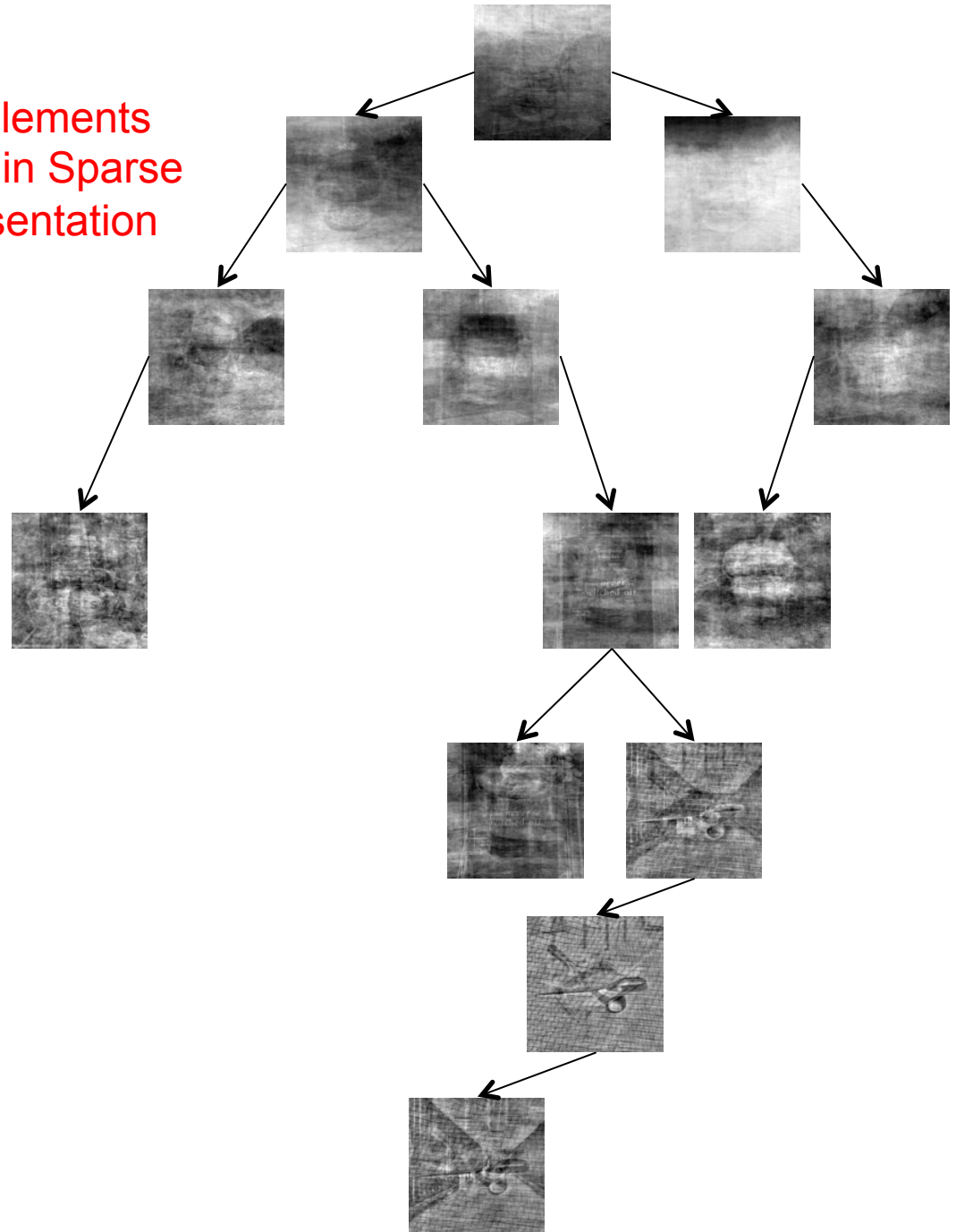
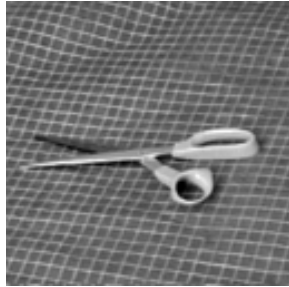
# Learned Orthogonal *Tree-Basis* Elements



(First four levels of 7 total)

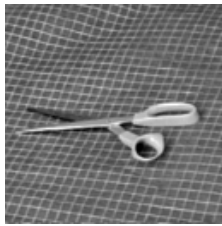
Tree Elements  
Present in Sparse  
Representation

Original Image

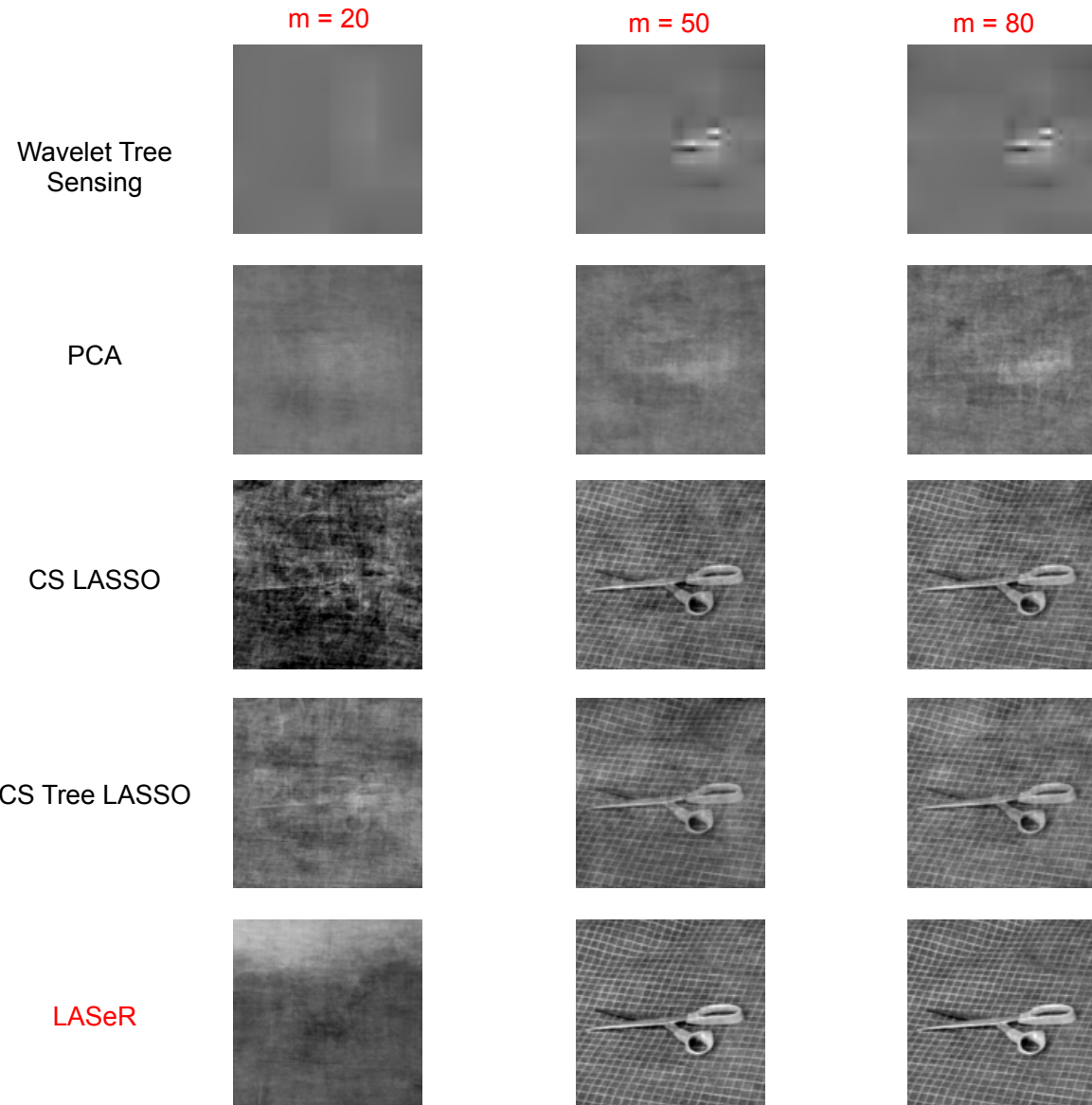


# Qualitative Results

“Sensing Energy”  
 $R = 128 \times 128$



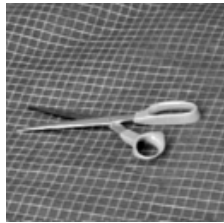
original image



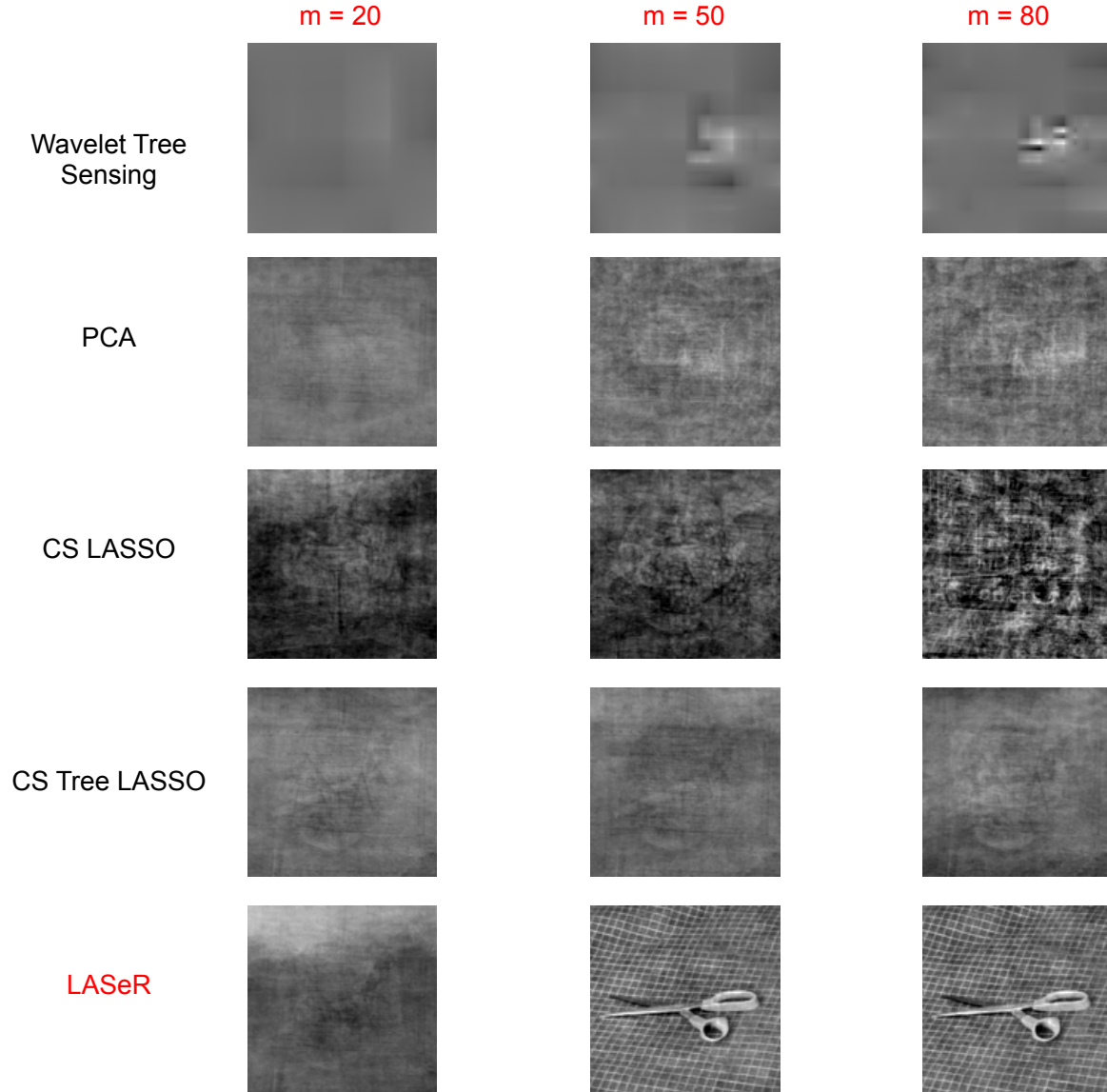
# Qualitative Results

“Sensing Energy”

$$R = \frac{128 \times 128}{32}$$



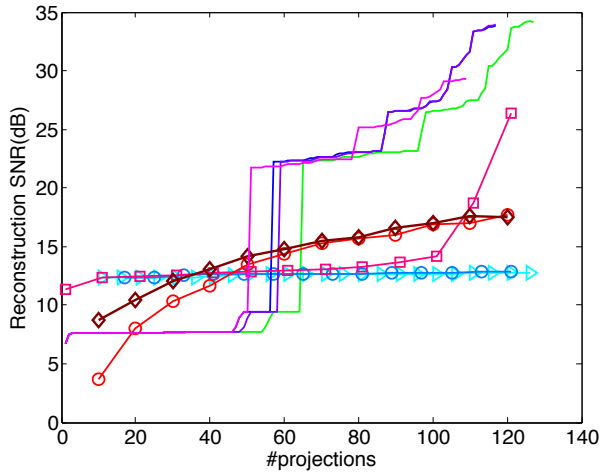
original image



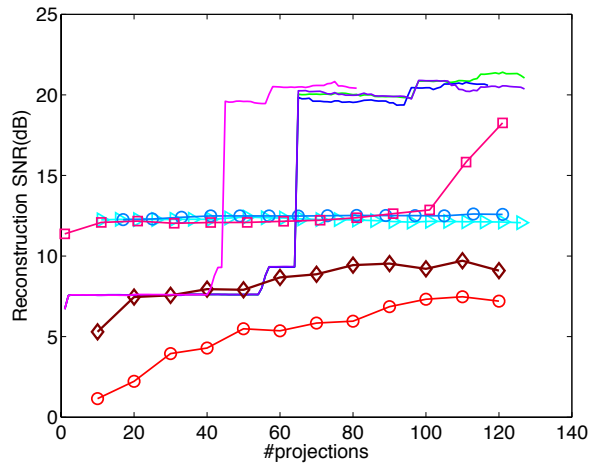


# Quantitative Results

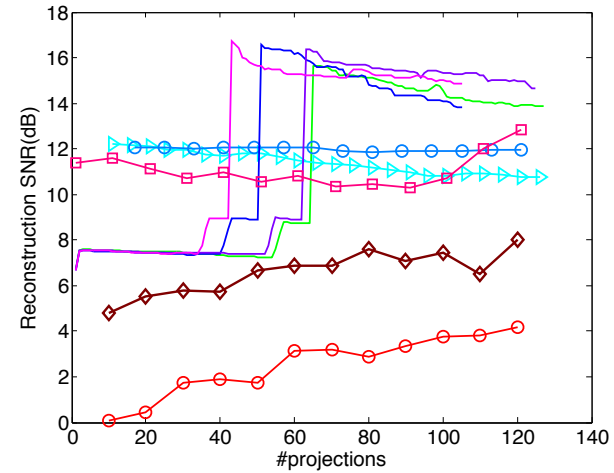
$\sigma = 1$



$R = (128 \times 128)$



$R = (128 \times 128)/32$



$R = (128 \times 128)/128$

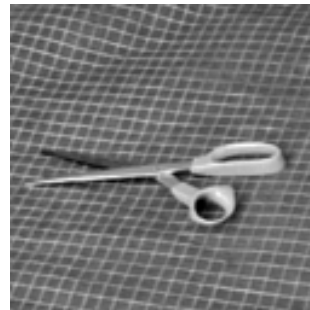
—: LASeR

□: PCA

o: CS Lasso

◇: CS Tree Lasso

o: Wavelet Sensing



original image

$$SNR = 10 \log_{10} \left( \frac{\|x\|_2^2}{\|\hat{x} - x\|_2^2} \right).$$

– *LASeR* –

*Imaging via “Patch-wise” Sensing*

# “Patch-wise” Sensing Experiment

Motivated by EO Imaging Application (Thanks: Bob Muisse @ Lockheed Martin)

Training Data:

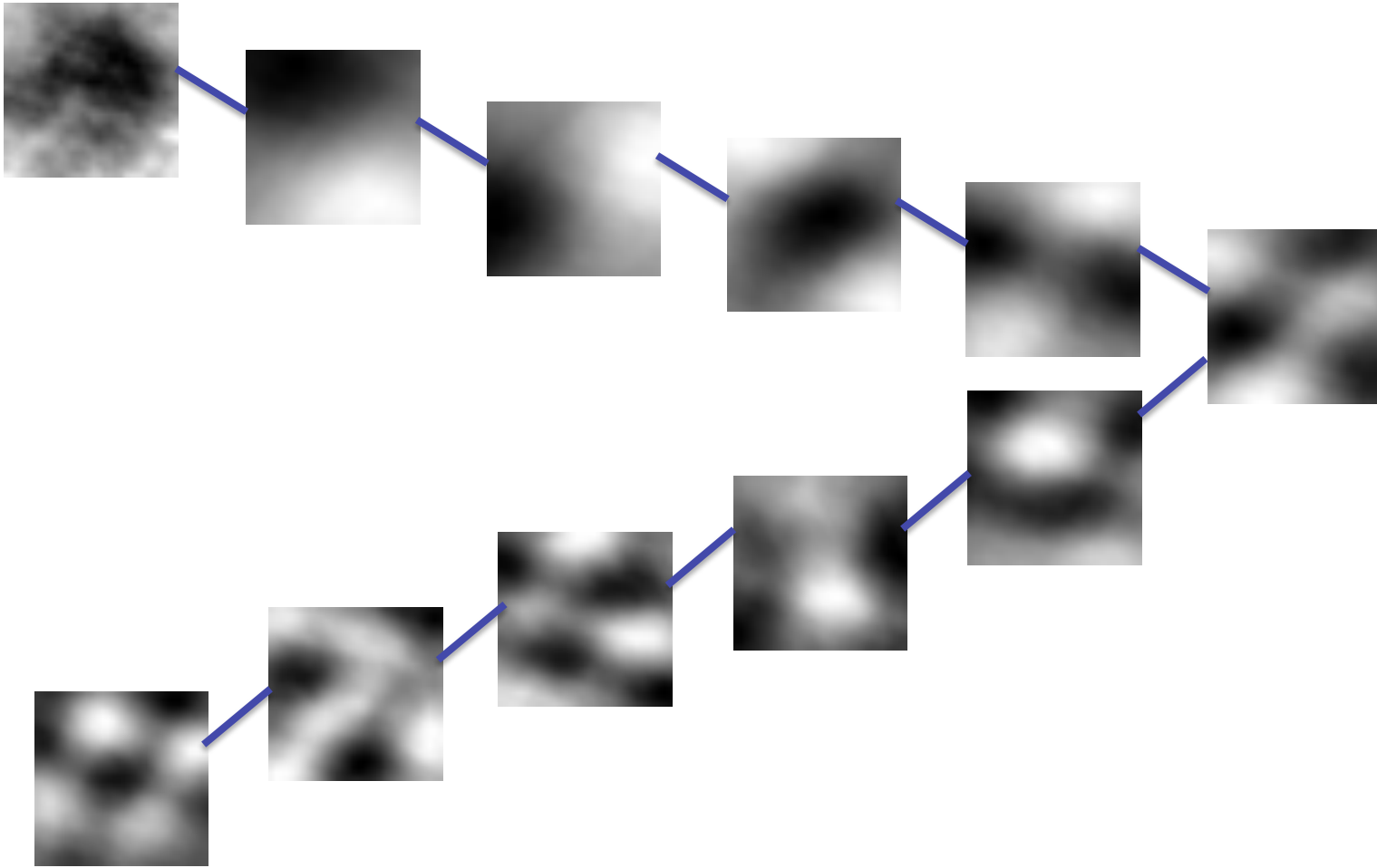
3 Sample images from the Columbus Large Image Format (CLIF) 2007 Dataset  
Each image is 1024x1024



Randomly extracted 3000 32x32 patches (at random locations)...  
and vectorized them into length 1024 vectors

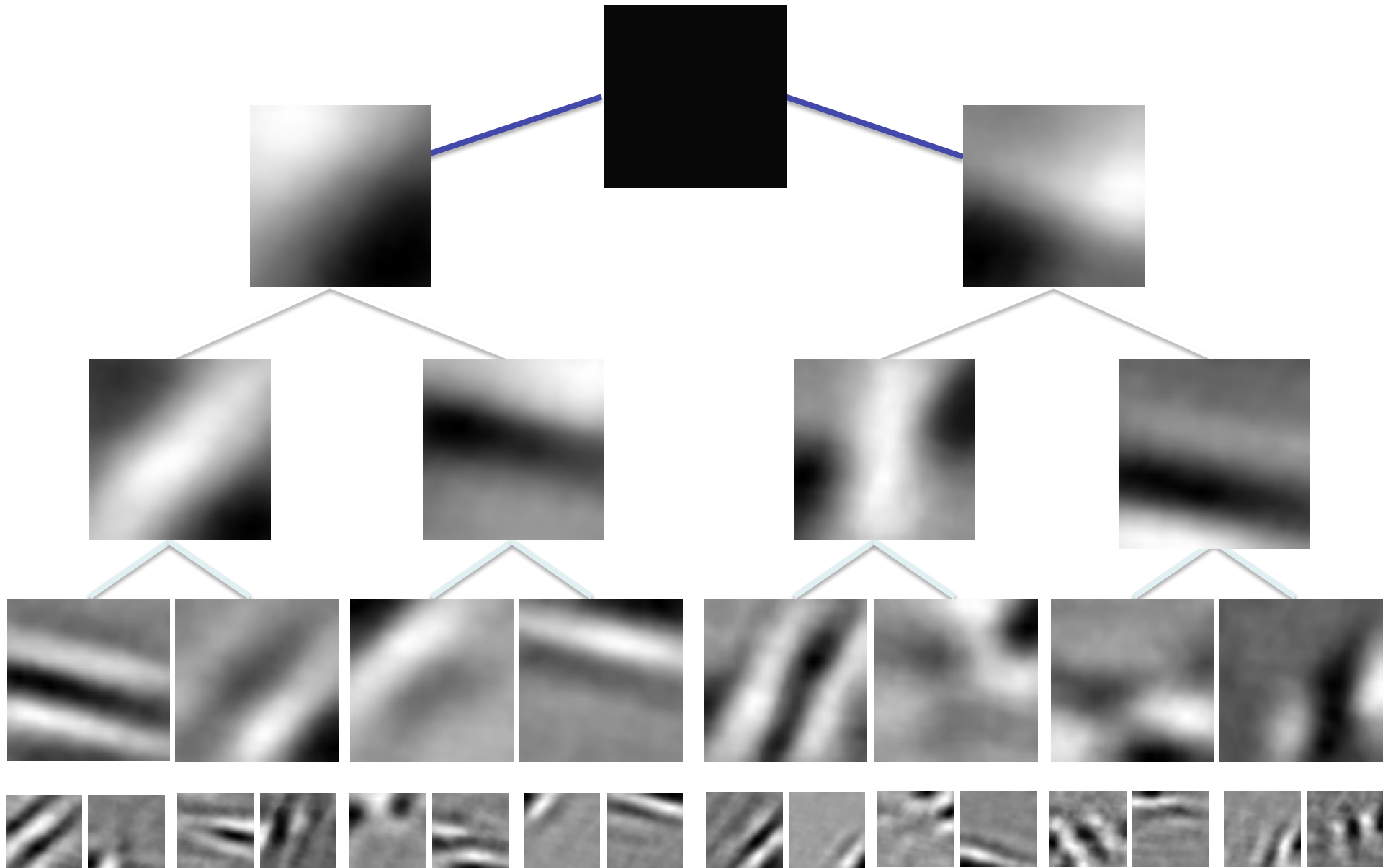
Applied PCA and LAsER (7-level 127 node binary tree) to this training data

# Compare: PCA Basis Elements



In the tree-sensing context, can view PCA sensing approach in terms of a tree of degree 1

# Learned Orthogonal *Tree-Basis* Elements



# Example: Approximation by “Patch-wise” Sensing

Test Image (another image from CLIF database)



Sense & reconstruct non-overlapping  $32 \times 32$  patches...  
...comparing LAsER, PCA, Wavelets...



# Approximation Results – Uniform Sampling Rate

Sampling rate: 12.5%



LASer  
rSNR = 16.5 dB



PCA  
rSNR = 17.6 dB

$$\text{rSNR} \triangleq -20 \log_{10}(\|\hat{x} - x\|_F / \|x\|_F)$$

# Approximation Results – Uniform Sampling Rate

Sampling rate: 12.5%



LASeR  
rSNR = 16.5 dB

$$\text{rSNR} \triangleq -20 \log_{10}(\|\hat{x} - x\|_F / \|x\|_F)$$



# Approximation Results – Uniform Sampling Rate

Sampling rate: 12.5%



PCA  
rSNR = 17.6 dB

$$\text{rSNR} \triangleq -20 \log_{10}(\|\hat{x} - x\|_F / \|x\|_F)$$

# Approximation Results – Uniform Sampling Rate

Sampling rate: 12.5%



LASeR  
rSNR = 16.5 dB



2D Haar Wavelet  
rSNR = 13.5 dB

$$\text{rSNR} \triangleq -20 \log_{10}(\|\hat{x} - x\|_F / \|x\|_F)$$

# Approximation Results – Adaptive Sampling Rate

Average sampling rate: 7.2%



LAsER  
rSNR = 13.9 dB



PCA  
rSNR = 15.0 dB

$$\text{rSNR} \triangleq -20 \log_{10}(\|\hat{x} - x\|_F / \|x\|_F)$$

# Approximation Results – Adaptive Sampling Rate

Average sampling rate: 7.2%



LASeR  
rSNR = 13.9 dB



2D Haar Wavelet  
rSNR = 11.9 dB

$$\text{rSNR} \triangleq -20 \log_{10}(\|\hat{x} - x\|_F / \|x\|_F)$$

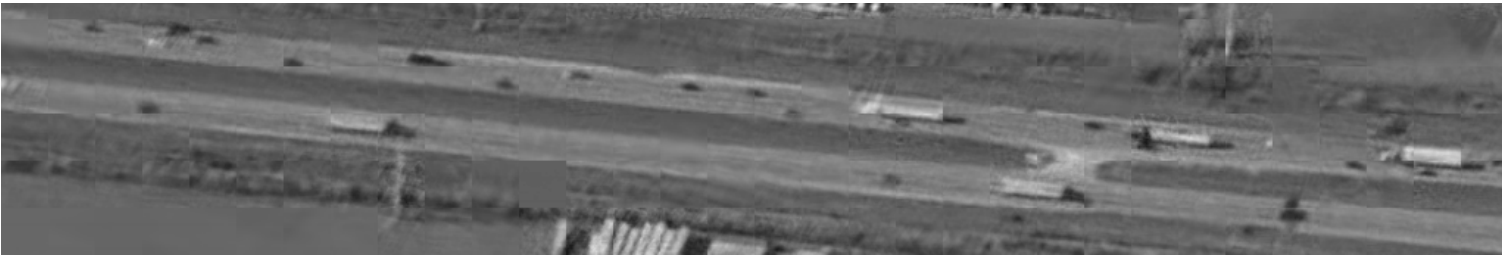


# Approximation: Zoomed In

A Closer Look... (Average sampling rate: 7.2%)



Original



LASeR



PCA



2D  
Haar

# Approximation: Zoomed In

A Closer Look... (Average sampling rate: 7.2%)



Original



LAsE-R



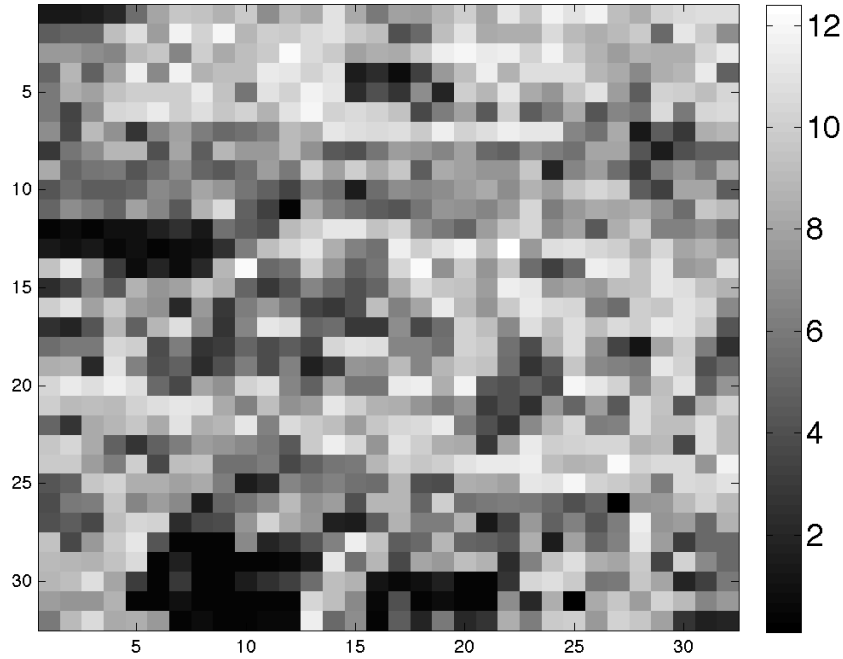
PCA



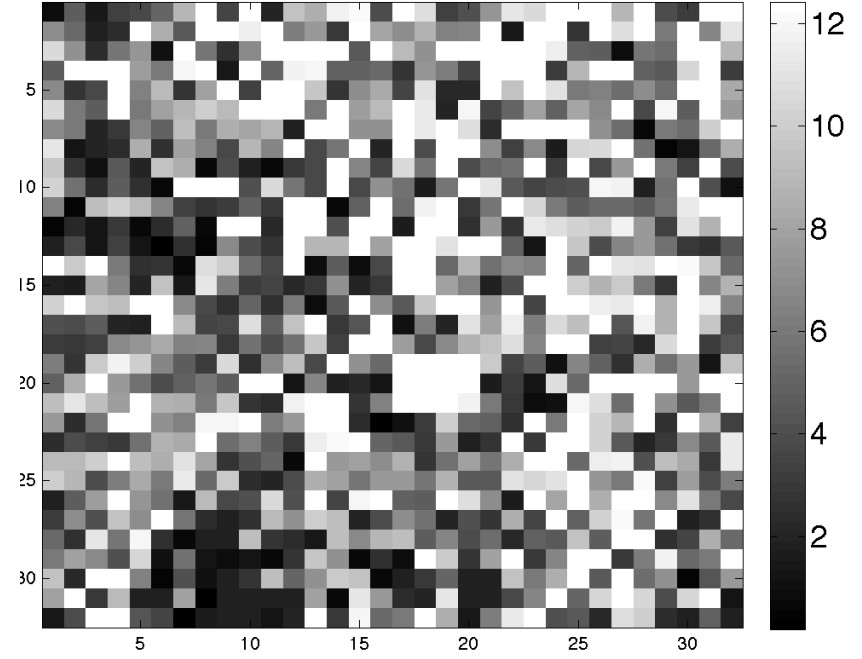
2D  
Haar

# Sampling Rate Adapts to Block “Complexity”

Sampling rate per block (Average sampling rate: 7.2%)



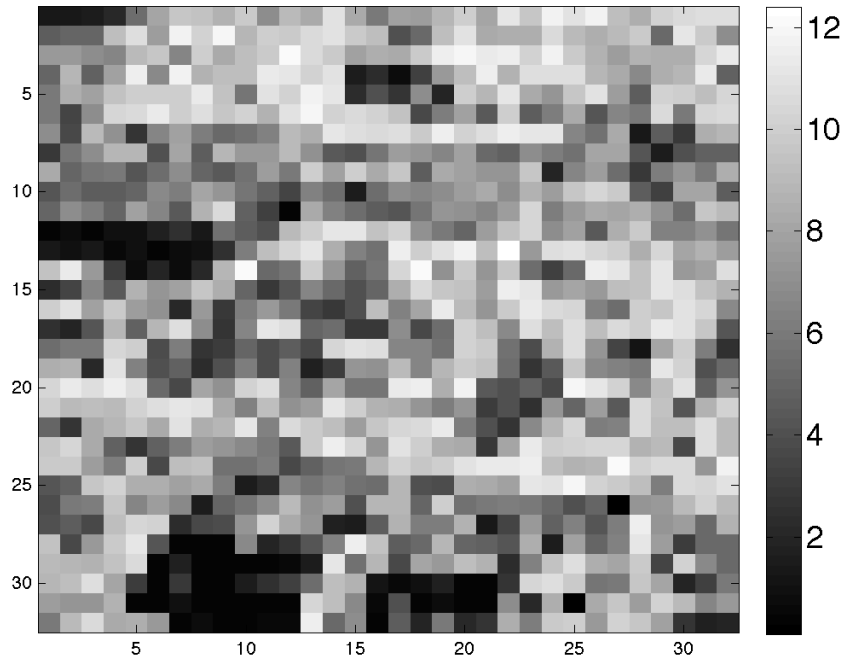
LAsER



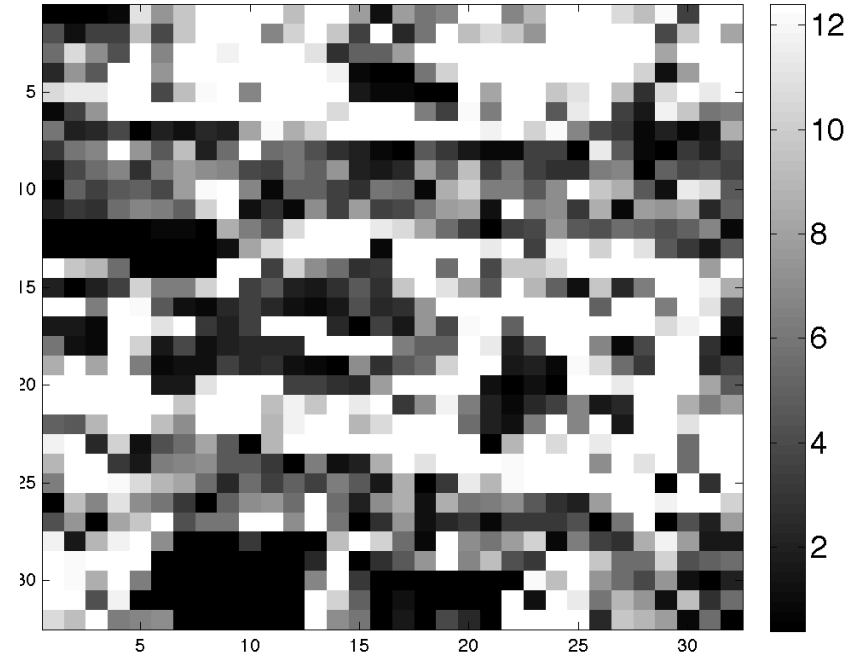
PCA

# Sampling Rate Adapts to Block “Complexity”

Sampling rate per block (Average sampling rate: 7.2%)



LASeR



2D Haar



# Summary: Adaptivity + Structure

In Theory (Support Recovery)

	Non-structured	Structured	
Non-adaptive	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right) \log n}$	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right)}$ (conj.)	Non-adaptive
Adaptive	$\mu \geq \text{const.} \sqrt{\left(\frac{n}{R}\right) \log k}$	$\mu \geq \text{const.} \sqrt{\left(\frac{k}{R}\right) \log k}$	Adaptive
	Non-structured	Structured	

Conclusions:

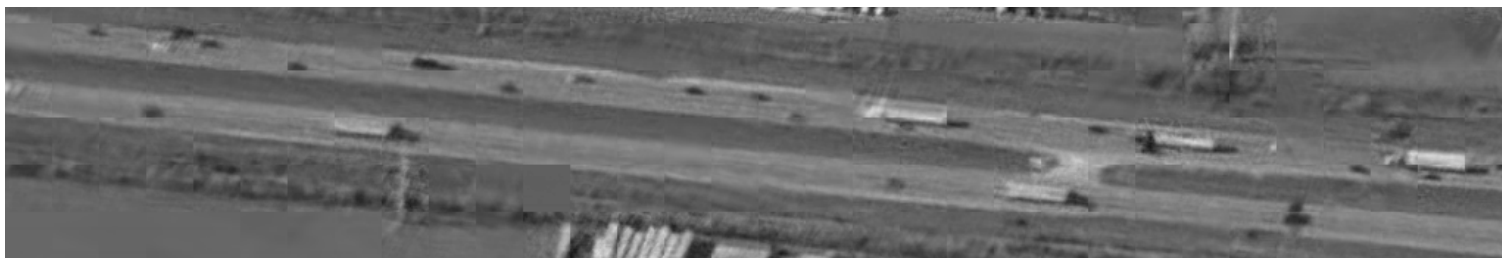
Polynomial reduction in SNR required for exact support recovery  
(for fixed “sensing energy”)

# Summary: Adaptivity + Structure

In Practice (Learned Representations and Patch-wise Sensing)



Original



LAsER

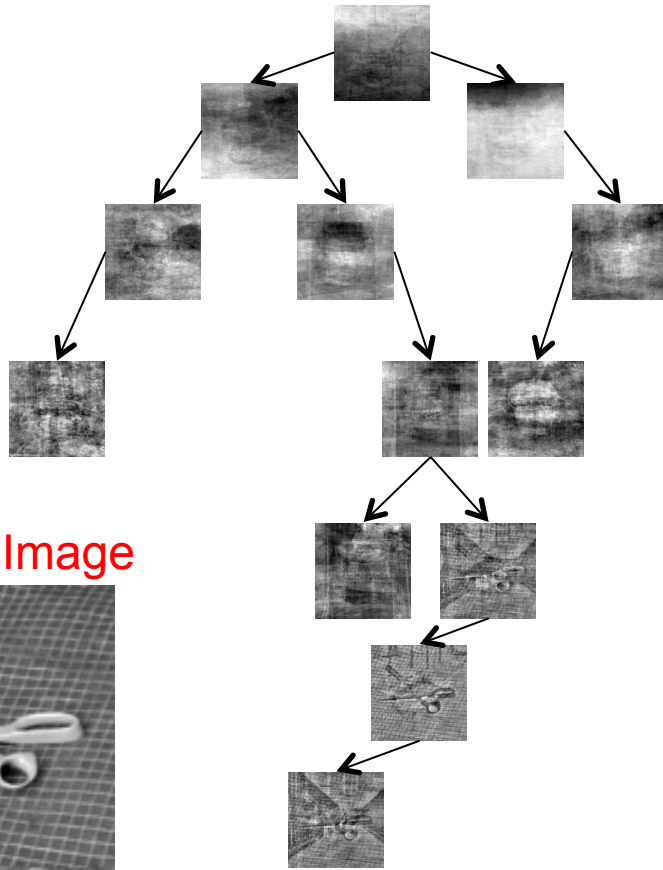


PCA

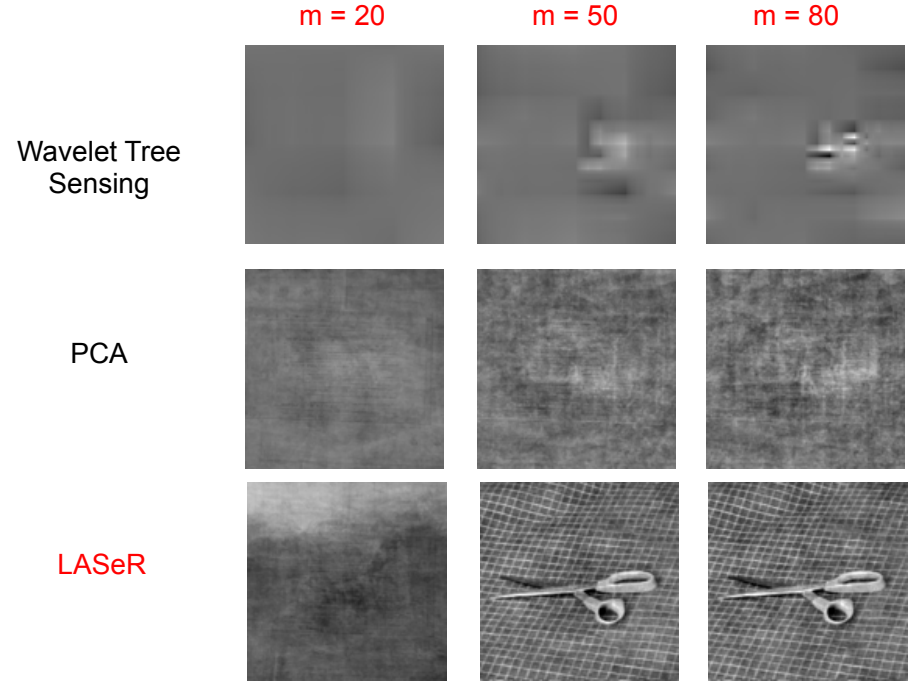
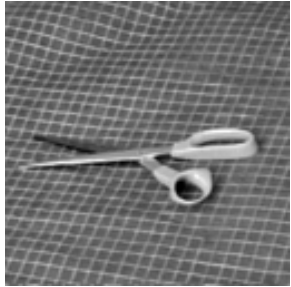
Conclusions:

PCA works very well on “small” patch sizes (shared, elemental structure) in noise free settings

# Summary: Adaptivity + Structure



Original Image



## Conclusions:

Potential benefit for learned representations depend on patch size, data “regularity”, noise.  
Use LASeR on PCA residuals? (ie, fuse PCA and LASeR)

Thank You!

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